

Density Functional Perturbation Theory and Phonons Calculations

Outline

- 1 Crystal lattice dynamics: phonons
- 2 Density functional perturbation theory
- 3 Codes for phonon dispersions

Description of a solid

Let's consider a periodic solid. We indicate with

$$\mathbf{R}_I = \mathbf{R}_\mu + \mathbf{d}_s$$

the equilibrium positions of the atoms. \mathbf{R}_μ indicate the Bravais lattice vectors and \mathbf{d}_s the positions of the atoms in one unit cell ($s = 1, \dots, N_{at}$).

We take N unit cells with Born-von Karman periodic boundary conditions. Ω is the volume of one cell and $V = N\Omega$ the volume of the solid.

At time t , each atom is displaced from its equilibrium position. $\mathbf{u}_I(t)$ is the displacement of the atom I .

Within the *Born-Oppenheimer adiabatic approximation* the nuclei move in a potential energy given by the total energy of the electron system calculated (for instance within DFT) at fixed nuclei. We call

$$E_{tot}(\mathbf{R}_I + \mathbf{u}_I)$$

this energy. The electrons are assumed to be in the ground state for each nuclear configuration.

If $|\mathbf{u}_I|$ is small, we can expand E_{tot} in a Taylor series with respect to \mathbf{u}_I . Within the *harmonic approximation*:

$$E_{tot}(\mathbf{R}_I + \mathbf{u}_I) = E_{tot}(\mathbf{R}_I) + \sum_{I\alpha} \frac{\partial E_{tot}}{\partial \mathbf{u}_{I\alpha}} \mathbf{u}_{I\alpha} + \frac{1}{2} \sum_{I\alpha, J\beta} \frac{\partial^2 E_{tot}}{\partial \mathbf{u}_{I\alpha} \partial \mathbf{u}_{J\beta}} \mathbf{u}_{I\alpha} \mathbf{u}_{J\beta} + \dots$$

where the derivatives are calculated at $\mathbf{u}_I = 0$ and α and β indicate the three Cartesian coordinates.

Equations of motion

At equilibrium $\frac{\partial E_{tot}}{\partial \mathbf{u}_{l\alpha}} = 0$, so the Hamiltonian of the ions becomes:

$$H = \sum_{l\alpha} \frac{\mathbf{P}_{l\alpha}^2}{2M_l} + \frac{1}{2} \sum_{l\alpha, j\beta} \frac{\partial^2 E_{tot}}{\partial \mathbf{u}_{l\alpha} \partial \mathbf{u}_{j\beta}} \mathbf{u}_{l\alpha} \mathbf{u}_{j\beta}$$

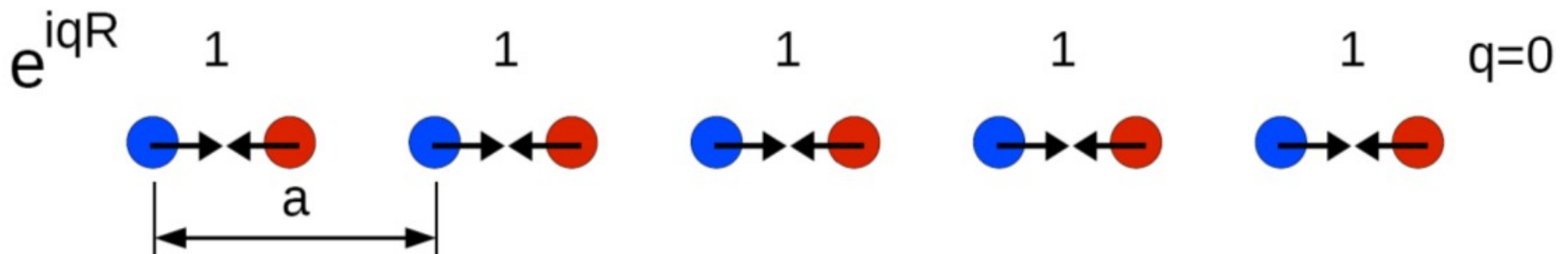
where \mathbf{P}_l are the momenta of the nuclei and M_l their masses. The classical motion of the nuclei is given by the $N \times 3 \times N_{at}$ functions $\mathbf{u}_{l\alpha}(t)$. These functions are the solutions of the Hamilton equations:

$$\begin{aligned} \dot{\mathbf{u}}_{l\alpha} &= \frac{\partial H}{\partial \mathbf{P}_{l\alpha}} \\ \dot{\mathbf{P}}_{l\alpha} &= -\frac{\partial H}{\partial \mathbf{u}_{l\alpha}} \end{aligned}$$

Vibrational properties

$$(\mathbf{R} + \tau_s)_{eq} \longrightarrow (\mathbf{R} + \tau_s)_{eq} + \mathbf{u}_{\mathbf{R}s}$$

$$\sum_{Rs\alpha} \frac{\mathbf{P}_{Rs\alpha}^2}{2M_s} + \frac{1}{2} \sum_{\substack{Rs\alpha \\ R's'\alpha'}} \mathbf{u}_{Rs\alpha} \frac{\partial^2 E_{el+ion}}{\partial \mathbf{u}_{Rs\alpha} \partial \mathbf{u}_{R's'\alpha'}} \mathbf{u}_{R's'\alpha'}$$



The phonon solution

We can search the solution in the form of a phonon. Let's introduce a vector \mathbf{q} in the first Brillouin zone. For each \mathbf{q} we can write:

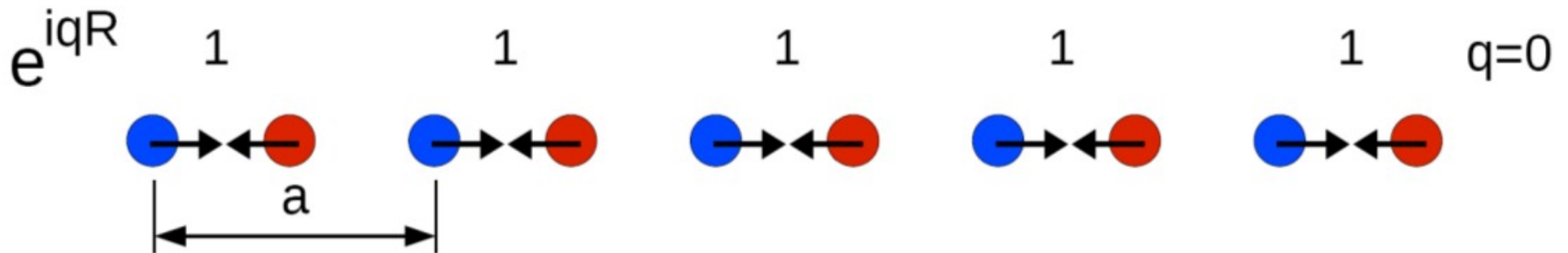
$$\mathbf{u}_{\mu s\alpha}(t) = \frac{1}{\sqrt{M_s}} \text{Re} \left[\mathbf{u}_{s\alpha}(\mathbf{q}) e^{i(\mathbf{q}\mathbf{R}_\mu - \omega_{\mathbf{q}}t)} \right]$$

where the time dependence is given by simple phase factors $e^{\pm i\omega_{\mathbf{q}}t}$ and the displacement of the atoms in each cell identified by the Bravais lattice \mathbf{R}_μ can be obtained from the displacements of the atoms in one unit cell, for instance the one that corresponds to $\mathbf{R}_\mu = 0$: $\frac{1}{\sqrt{M_s}} \mathbf{u}_{s\alpha}(\mathbf{q})$.

Vibrational properties

$$(\mathbf{R} + \tau_s)_{eq} \longrightarrow (\mathbf{R} + \tau_s)_{eq} + \mathbf{u}_s^{\mathbf{q}} \frac{e^{i\mathbf{q}\mathbf{R}}}{\sqrt{N}}$$

$$\sum_{s\alpha} \frac{\mathbf{P}_{s\alpha}^2}{2M_s} + \frac{1}{2} \sum_{\substack{s\alpha \\ 's'\alpha'}} \mathbf{u}_{s\alpha}^{\mathbf{q}*} \frac{\partial^2 E_{el+ion}}{\partial \mathbf{u}_{s\alpha}^{\mathbf{q}*} \partial \mathbf{u}_{'s'\alpha'}^{\mathbf{q}}} \mathbf{u}_{'s'\alpha'}^{\mathbf{q}}$$

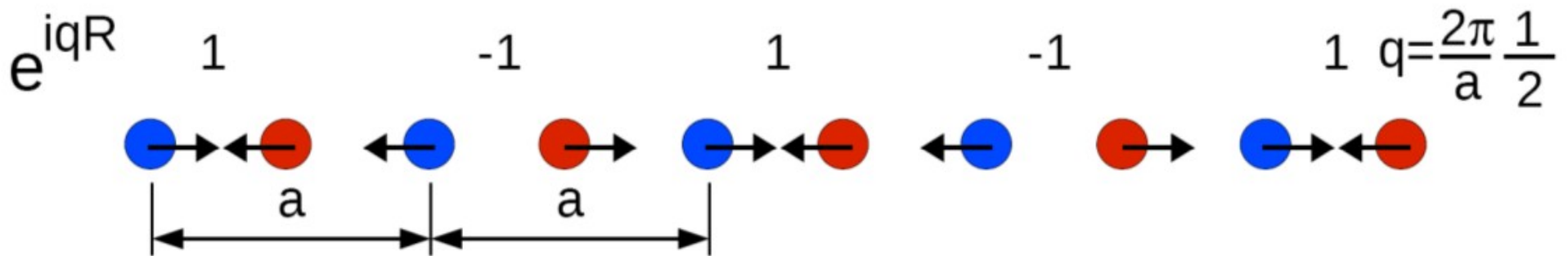


$$\Delta V_{ext}(r) = \sum_{\mathbf{R}_s} \frac{\partial V_s}{\partial \mathbf{R}} (|\mathbf{r} - \mathbf{R} - \tau_s|) \mathbf{u}_s^{\mathbf{q}} \frac{e^{i\mathbf{q}\mathbf{R}}}{\sqrt{N}}$$

Vibrational properties

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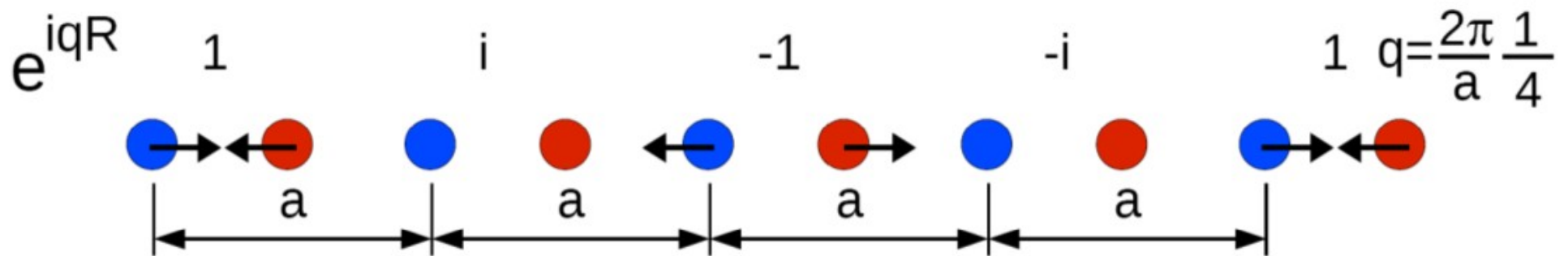


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The phonon solution-II

Inserting this solution in the equations of motion and writing $I = (\mu, s)$, $J = (\nu, s')$ we obtain an eigenvalue problem for the $3 \times N_{at}$ variables $\mathbf{u}_{s\alpha}(\mathbf{q})$:

$$\omega_{\mathbf{q}}^2 \mathbf{u}_{s\alpha}(\mathbf{q}) = \sum_{s'\beta} D_{s\alpha s'\beta}(\mathbf{q}) \mathbf{u}_{s'\beta}(\mathbf{q})$$

where:

$$D_{s\alpha s'\beta}(\mathbf{q}) = \frac{1}{\sqrt{M_s M_{s'}}} \sum_{\nu} \frac{\partial^2 E_{tot}}{\partial \mathbf{u}_{\mu s\alpha} \partial \mathbf{u}_{\nu s'\beta}} e^{i\mathbf{q}(\mathbf{R}_{\nu} - \mathbf{R}_{\mu})}$$

is the dynamical matrix of the solid.

KS self-consistent equations

$$\left[-\frac{\hbar^2}{2m} \nabla^2 + V_{KS}(r) - \varepsilon_i \right] \varphi_i(r) = 0$$

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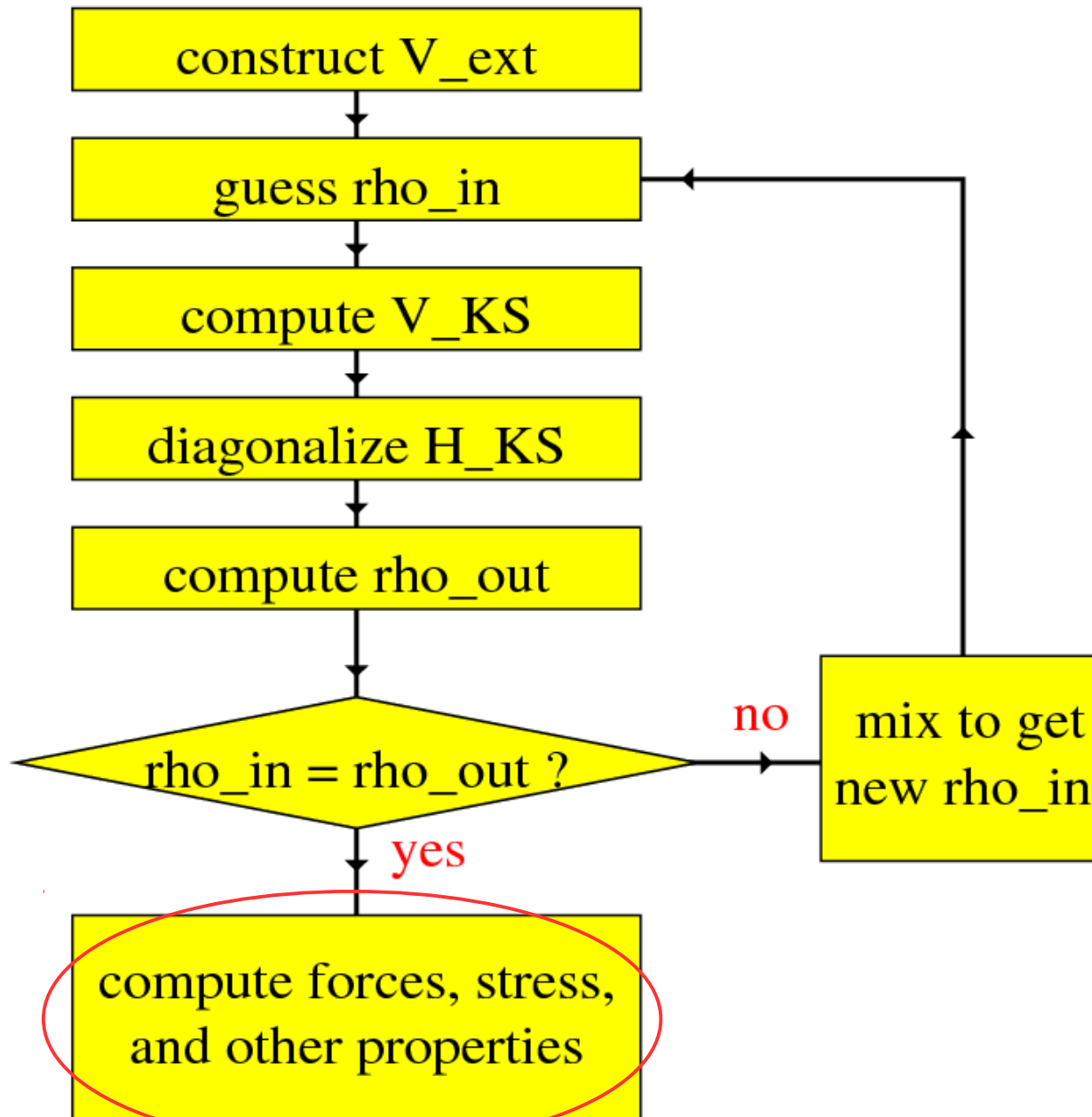
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$$\rightarrow V_{KS}(r) \rightarrow \varphi_i(r) \rightarrow \rho(r)$$

Structure of a self-consistent type code



Total KS energy

$$E_{el+ion} = -\frac{\hbar^2}{2m} \sum_i \langle \varphi_i | \nabla^2 | \varphi_i \rangle + \int V_{ext}(r) \rho(r) dr + \\ E_H[\rho] + E_{xc}[\rho] + E_{WLD}$$

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Hellmann-Feynman Theorem

$$F_{I\alpha} = -\frac{\partial E_{el+ion}}{\partial R_{I\alpha}} = -\int \frac{\partial V_{ext}(r)}{\partial R_{I\alpha}} \rho(r) dr - \frac{\partial E_{WLD}}{\partial R_{I\alpha}}$$

$$\frac{\partial E_{el+ion}}{\partial \lambda} = \int \frac{\partial V_{ext}(r)}{\partial \lambda} \rho(r) dr + \frac{\partial E_{WLD}}{\partial \lambda}$$

the linear variation of the GS density is not needed



KS energy expansion

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$$\frac{\partial E_{el+ion}}{\partial \lambda} = \int \frac{\partial V_{ext}(r)}{\partial \lambda} \rho(r) dr + \frac{\partial E_{WLD}}{\partial \lambda}$$

$$\frac{\partial^2 E_{el+ion}}{\partial \lambda \partial \mu} = \int \frac{\partial^2 V_{ext}(r)}{\partial \lambda \partial \mu} \rho(r) dr + \int \frac{\partial V_{ext}(r)}{\partial \lambda} \frac{\partial \rho(r)}{\partial \mu} dr + \frac{\partial^2 E_{WLD}}{\partial \lambda \partial \mu}$$

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$$\left[-\frac{\hbar^2}{2m} \nabla^2 + V_{KS}(r) - \varepsilon_i \right] \Delta \varphi_i(r) = -(\Delta V_{KS} - \Delta \varepsilon_i) \varphi_i(r)$$

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$$\Delta \rho(r) = 2 \sum_i \varphi_i^*(r) \Delta \varphi_i(r)$$

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$$\left[-\frac{\hbar^2}{2m} \nabla^2 + V_{KS}(r) - \varepsilon_i \right] \Delta \tilde{\varphi}_i(r) = -P_c \Delta V_{KS}(r) \varphi_i(r)$$

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$$\Delta V_{KS}(r) = \Delta V_{ext}(r) + e^2 \int \frac{\Delta \rho(r')}{|r - r'|} dr' + \int \frac{\delta v_{xc}(r)}{\delta \rho(r')} \Delta \rho(r') dr'$$

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$$\Delta V_{KS} \rightarrow \Delta \tilde{\varphi}_i(r) \rightarrow \Delta \rho(r)$$

Evaluate the dynamical matrix

$$\begin{aligned} \frac{\partial^2 E_{el+ion}}{\partial \lambda \partial \mu} = & \int \frac{\partial^2 V_{ext}(r)}{\partial \lambda \partial \mu} \rho(r) dr + \int \frac{\partial V_{ext}(r)}{\partial \lambda} \frac{\partial \rho(r)}{\partial \mu} dr \\ & + \frac{\partial^2 E_{WLD}}{\partial \lambda \partial \mu} \end{aligned}$$

Dynamical matrix at finite \mathbf{q} - II

Defining:

$$\frac{\partial^2 V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}^*(\mathbf{q}) \partial \mathbf{u}_{s'\beta}(\mathbf{q})} = \frac{1}{\sqrt{M_s M_{s'}}} \sum_{\mu\nu} e^{-i\mathbf{q}\mathbf{R}_\mu} \frac{\partial^2 V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{\mu s\alpha} \partial \mathbf{u}_{\nu s'\beta}} e^{i\mathbf{q}\mathbf{R}_\nu}$$

we can show (see below) that $\frac{\partial^2 V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}^*(\mathbf{q}) \partial \mathbf{u}_{s'\beta}(\mathbf{q})}$ is a lattice-periodic function. Then we can define

$$\frac{\partial \rho(\mathbf{r})}{\partial \mathbf{u}_{s'\beta}(\mathbf{q})} = \frac{1}{\sqrt{M_{s'}}} \sum_{\nu} \frac{\partial \rho(\mathbf{r})}{\partial \mathbf{u}_{\nu s'\beta}} e^{i\mathbf{q}\mathbf{R}_\nu}$$

and show that $\frac{\partial \rho(\mathbf{r})}{\partial \mathbf{u}_{s'\beta}(\mathbf{q})} = e^{i\mathbf{q}\mathbf{r}} \frac{\tilde{\partial} \rho(\mathbf{r})}{\partial \mathbf{u}_{s'\beta}(\mathbf{q})}$, where $\frac{\tilde{\partial} \rho(\mathbf{r})}{\partial \mathbf{u}_{s'\beta}(\mathbf{q})}$ is a lattice-periodic function.

Dynamical matrix at finite \mathbf{q} - III

In the same manner, by defining

$$\left(\frac{\partial V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}(\mathbf{q})} \right)^* = \frac{1}{\sqrt{M_s}} \sum_{\mu} e^{-i\mathbf{q}\mathbf{R}_{\mu}} \frac{\partial V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{\mu s\alpha}}$$

and showing that $\frac{\partial V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}(\mathbf{q})} = e^{i\mathbf{q}\mathbf{r}} \frac{\partial \tilde{V}_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}(\mathbf{q})}$, where $\frac{\partial \tilde{V}_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}(\mathbf{q})}$ is a lattice-periodic function, we can write the dynamical matrix at finite \mathbf{q} as:

$$D_{s\alpha s'\beta}(\mathbf{q}) = \int_{\Omega} d^3r \frac{\partial^2 V_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}^*(\mathbf{q}) \partial \mathbf{u}_{s'\beta}(\mathbf{q})} \rho(\mathbf{r}) + \int_{\Omega} d^3r \left(\frac{\partial \tilde{V}_{loc}(\mathbf{r})}{\partial \mathbf{u}_{s\alpha}(\mathbf{q})} \right)^* \left(\frac{\partial \tilde{\rho}(\mathbf{r})}{\partial \mathbf{u}_{s'\beta}(\mathbf{q})} \right).$$

ph.x

The program `ph.x` solves this self-consistent linear system for $3 \times N_{at}$ perturbations at a fixed vector \mathbf{q} . With $\frac{\partial \rho(\mathbf{r})}{\partial \mathbf{u}_{s'\beta}(\mathbf{q})}$ for all perturbations, it calculates the dynamical matrix

$$D_{s\alpha s'\beta}(\mathbf{q})$$

at the given \mathbf{q} as discussed above. Diagonalizing this matrix we obtain $3 \times N_{at}$ frequencies $\omega_{\mathbf{q}}$. By repeating this procedure for several \mathbf{q} we could plot $\omega_{\mathbf{q}}$ as a function of \mathbf{q} and display the phonon dispersions. However, it is more convenient to adopt a different approach that requires the calculation of the dynamical matrix in a small set of vectors \mathbf{q} .

Phonon dispersions

The dynamical matrix of the solid:

$$D_{s\alpha s'\beta}(\mathbf{q}) = \frac{1}{\sqrt{M_s M_{s'}}} \sum_{\nu} \frac{\partial^2 E_{tot}}{\partial \mathbf{u}_{\mu s\alpha} \partial \mathbf{u}_{\nu s'\beta}} e^{i\mathbf{q}(\mathbf{R}_{\nu} - \mathbf{R}_{\mu})} \quad (1)$$

is a periodic function of \mathbf{q} with $D_{s\alpha s'\beta}(\mathbf{q} + \mathbf{G}) = D_{s\alpha s'\beta}(\mathbf{q})$ for any reciprocal lattice vector \mathbf{G} . Furthermore, due to the translational invariance of the solid, it does not depend on μ . Eq.1 is a Fourier expansion of a three dimensional periodic function. We have Fourier components only at the discrete values \mathbf{R}_{ν} of the Bravais lattice and we can write:

$$\frac{1}{\sqrt{M_s M_{s'}}} \frac{\partial^2 E_{tot}}{\partial \mathbf{u}_{\mu s\alpha} \partial \mathbf{u}_{\nu s'\beta}} = \frac{\Omega}{(2\pi)^3} \int d^3\mathbf{q} D_{s\alpha s'\beta}(\mathbf{q}) e^{-i\mathbf{q}(\mathbf{R}_{\nu} - \mathbf{R}_{\mu})}.$$

Discrete Fourier transform

We can use the properties of the discrete Fourier transform and sample the integral in a uniform mesh of \mathbf{q} vectors. This will give the inter-atomic force constants only for a certain range of values of \mathbf{R}_ν neighbors of \mathbf{R}_μ .

In order to recall the main properties of the discrete Fourier transform, let us consider a one dimensional periodic function $f(x + a) = f(x)$ with period a . This function can be expanded in a Fourier series and will have a discrete set of Fourier components at $k_n = \frac{2\pi}{a}n$, where n is an integer (positive, negative or zero).

$$f(x) = \sum_n c_n e^{ik_n x}$$

where the coefficients of the expansion are:

Discrete Fourier transform - II

$$c_n = \frac{1}{a} \int_0^a f(x) e^{-ik_n x} dx.$$

In general, if $f(x)$ is a sufficiently smooth function, $c_n \rightarrow 0$ at large n . Now suppose that we discretize $f(x)$ in a uniform set of N points $x_j = j\Delta x$ where $\Delta x = a/N$ and $j = 0, \dots, N-1$, then we can calculate:

$$\tilde{c}_n = \frac{1}{N} \sum_{j=0}^{N-1} f(x_j) e^{-i\frac{2\pi}{N} nj},$$

\tilde{c}_n is a periodic function of n and $\tilde{c}_{n+N} = \tilde{c}_n$. So, if N is sufficiently large that $c_n = 0$ when $|n| \geq N/2$, \tilde{c}_n is a good approximation of c_n for $|n| < N/2$ and the function

q2r.x

$C_{s\alpha s'\beta}(\mathbf{R}) = \frac{\partial^2 E_{tot}}{\partial \mathbf{u}_{\mu s\alpha} \partial \mathbf{u}_{\nu s'\beta}}$ and write the relationship:

$$C_{s\alpha s'\beta}(\mathbf{R}) = \frac{1}{N_q} \sum_{i=1}^{N_q} C_{s\alpha s'\beta}(\mathbf{q}_i) e^{i\mathbf{q}_i \mathbf{R}}.$$

The code `q2r.x` reads a set of dynamical matrices obtained for a uniform mesh of \mathbf{q}_i vectors and calculates, using this equation, the inter-atomic force constants for some neighbors of the point $\mathbf{R} = 0$.

matdyn.x

If the dynamical matrix is a sufficiently smooth function of \mathbf{q} , the inter-atomic force constants decay sufficiently rapidly in real space and we can use Eq. 1 limiting the sum over ν to the few neighbors of \mathbf{R}_μ for which we have calculated the inter-atomic force constants. With the present notation Eq. 1 becomes:

$$C_{s\alpha s'\beta}(\mathbf{q}) = \sum_{\mathbf{R}} C_{s\alpha s'\beta}(\mathbf{R}) e^{-i\mathbf{q}\mathbf{R}}, \quad (3)$$

a relationship that allows the interpolation of the dynamical matrix at arbitrary \mathbf{q} , by a few inter-atomic force constants. The program `matdyn.x` reads the inter-atomic force constants calculated by `q2r.x` and calculates the dynamical matrices at an arbitrary \mathbf{q} using this equation.

This procedure fails in two cases:

- In metals when there are Kohn anomalies. In this case $D_{s\alpha s'\beta}(\mathbf{q})$ is not a smooth function of \mathbf{q} and the inter-atomic force constants are long range.
- In polar insulators where the atomic displacements generate long range electrostatic interactions and the dynamical matrix is non analytic for $\mathbf{q} \rightarrow 0$. This case, however, can be dealt with by calculating the Born effective charges and the dielectric constant of the material.

Use of symmetry

Phonon dispersions require the DFPT calculation on a uniform mesh $N_{q_1} \times N_{q_2} \times N_{q_3} = N_q$ of \mathbf{q} vectors. The CPU time can be roughly estimated as

$$N_q \times 3 \times N_{\text{at}} \times T_{\text{scf}}$$

where T_{scf} is the CPU time of a single self-consistent calculation. Using symmetry the \mathbf{q} -vector mesh is reduced to a set of \bar{N}_q non equivalent \mathbf{q} vectors. The calculation of the dynamical matrix at each \mathbf{q} vector requires an amount of CPU time roughly proportional to the size of its star of \mathbf{q} vectors. So low symmetry \mathbf{q} vectors require much more CPU time than high symmetry \mathbf{q} vectors mainly because ph. x uses only the symmetries of the small group of \mathbf{q} to reduce the \mathbf{k} points.

Use of symmetry - II

On the other hand, from the dynamical matrix at \mathbf{q} we can obtain, for free, the dynamical matrices of the star of \mathbf{q} that is larger for low symmetry \mathbf{q} . Not all the $3 \times N_{\text{at}}$ perturbations have to be calculated simultaneously at each \mathbf{q} . Choosing displacement patterns that transform according to an irreducible representation (irrep) of the small group of \mathbf{q} , the number of patterns that transform among themselves is equal to the dimension of the irreducible representation. For standard point groups the maximum dimension is 3, while for \mathbf{q} at zone border and nonsymmorphic point groups the maximum dimension could be larger, up to 6.

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