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Mike Johnston, "Spaceman with Floating Pizza







Hackathon Sat.1

QUANTUM ESPRESSO & GPU survival guide

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Once upon a time and now

One of the first (1985) commercial massively parallel machines, the Connection Machine CM-1, now on display in a museum.

It was an innovative advanced machine, expensive and really fast, and really hard to program.

For a few thousands \$\$ now you may have the modern equivalent of a CM under your desk (not recommended: it is hot and noisy).

The hard part: programming it ... !



GPU basics (hardware)

- Accelerated hybrid architectures, aka GPUs (graphical processing units), are the current "big thing" in high-performance computing (HPC). The main reason: *more Flops per Watt* than conventional architectures.
- GPUs are a specialized piece of hardware that work like FPUs (floating-point units) "on steroids": they are physically connected to a conventional node and perform specific mathematical operations, exploiting a massive *internal parallelism* of the GPU.
- In a typical configuration, a few GPUs (say 1 to 4) are connected to a multi-core node with a few tens of cores (say 32 to 128). Big machines for HPC have many multi-core nodes, part or all of which have one or more GPUs.
- The GPUs have an *internal fast memory* that may be quite large (tens of Gb). The memory is fixed: you cannot buy a memory upgrade.
- GPUs do not directly access data on disk or other peripherals, they do that *via the CPU*. Depending upon the configuration, the GPUs of a single node may (or may not) directly communicate between them, e.g., via MPI calls.

Current GPU brands: NVidia, AMD, Intel

GPU basics (software)

- The code (or a single MPI process) runs on the CPU, transfers data to/from the GPU, instructs the GPU to make specific computations on those data.
- If your code/MPI process runs out of GPU memory, you are out of luck.
- GPUs are really fast when performing many operations in parallel, thus exploiting the internal parallelism. In this respect, they behave like old vector or parallel machines.
- GPUs are really fast if data is already on GPU, but moving data from CPU to GPU and vice versa is slow and *must be kept to the strict minimum*.
- Currently there is no way to write code for GPU using machine-independent portable coding, and no automatic acceleration either. Each GPU brand comes with its own set of compilers, libraries, supported languages.
 - ▶ NVidia: CUDA software stack, CUDA Fortran extensions, OpenACC directives
 - AMD: ROCm software stack, OpenMP v.5 directives
 - Intel: oneAPI software stack, OpenMP v.5 directives

MaX goals and philosophy

A software infrastructure for

- Sustainable software development
- Performance portability

for exascale applications(*), via:

- Separation of concerns: scientists work on science (top layers in figure), IT people on computers (bottom layers)
- Co-design:

scientists and IT people work together with hardware vendors

(*) suitable for exascale machines, that is, capable of 10^{18} flops





Porting to heterogeneous architectures



The QUANTUM ESPRESSO suite has been accelerated using a mixed CUDA Fortran/OpenACC scheme. A version based on OpenMP offloading is under heavy development, in order to enhance portability to hardware from different vendors.

A rather dumb example of CUDA Fortran

```
USE cudafor
attributes( device ) :: h_d, s_d, e_d, psi_d
. . .
!$cuf kernel do(3) <<<*,*>>>
do ipol=1,npol
   do k = 1. m
      do i = 1. n
         denm = h_d (i,ipol) - e_d (k) * s_d (i,ipol)
         if (abs (denm) < eps) denm = sign (eps, denm)
         psi_d (i, ipol, k) = psi_d (i, ipol, k) / denm
      enddo
   enddo
enddo
psi = psi_d
. . .
```

Arrays with attribute DEVICE are on device (GPU), all others are on host (CPU)

GPU survival guide (Paolo Giannozzi)

An equally dumb example with OpenACC

```
. . .
!$acc present( h, s, e, psi)
. . .
!$acc parallel loop collapse(3)
do ipol=1,npol
   do k = 1, m
      do i = 1, n
         denm = h (i,ipol) - e_d (k) * s (i,ipol)
         if (abs (denm) < eps) denm = sign (eps, denm)
         psi (i, ipol, k) = psi (i, ipol, k) / denm
      enddo
   enddo
enddo
!$acc update host(psi)
. . .
```

Arrays can copied from host (CPU) to device (GPU) and vice versa

Towards a portable GPU version

The transition from CUDA to Openacc



GPU and $\operatorname{QUANTUM}\,\operatorname{ESPRESSO:}$ state of the art

Currently, the development of $\operatorname{QUANTUM}\,\operatorname{ESPRESSO}$ for GPUs relies on

- OpenACC for NVidia GPUs.
 CUDA Fortran is being slowly phased out (with a few exceptions)
 Work still ongoing (and will always be) but basically production-ready
- OpenMP v.5 for AMD and Intel GPUs Experimental, approaching production-ready state for AMD (LUMI) Available as a branch of the development git repository

Running on GPUs, in practice

In general: most GPUs, notably ALL cheap ones, do not have double-precision floating-point operations as main target. Do not expect spectacular performances from those GPUs.

Relevant parameters affecting performances are

- 1. Floating-point GPU performances (increases for increasing \$\$\$)
- 2. Available GPU memory (the more, the better, but of course more \$\$\$)
- 3. How well one can distribute the load (see below)

In general: use GPU wisely, not massively. Quality instead of quantity!

- 1. *Run one MPI process per GPU*. Oversubscription, i.e., running multiple MPI processing on a GPU, is seldom a good idea.
- 2. *Prefer low-communication parallelization levels*: k-points for scf calculations, wave-vectors and irreps for phonon calculation, whatever is available.
- 3. Use plane-wave parallelization *only if you need to distribute memory*. Each MPI process has to fit into the memory of the connected GPU. Plane-wave parallelization works well but it involves significant inter-GPU communications. Use GPU MPI if available.

Some references

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